

# ECED 3300

## Tutorial 1

### Problem 1

Show that the vector components of  $\mathbf{A}$  **parallel** and **perpendicular** to a given vector  $\mathbf{a}_s$  can be expressed as

$$(a) \mathbf{A}_{\parallel} = (\mathbf{A} \cdot \mathbf{a}_s)\mathbf{a}_s;$$

$$(b) \mathbf{A}_{\perp} = \mathbf{a}_s \times (\mathbf{A} \times \mathbf{a}_s).$$

### Solution

(a) By definition of the scalar product,  $|\mathbf{A}_{\parallel}| = (\mathbf{A} \cdot \mathbf{a}_s)$  as  $\mathbf{a}_s$  is a unit vector. It follows at once that  $\mathbf{A}_{\parallel} = |\mathbf{A}_{\parallel}|\mathbf{a}_s = (\mathbf{A} \cdot \mathbf{a}_s)\mathbf{a}_s$ .

(b) Using the “bac-cab” formula,  $\mathbf{a}_s \times (\mathbf{A} \times \mathbf{a}_s) = \mathbf{A}(\mathbf{a}_s \cdot \mathbf{a}_s) - \mathbf{a}_s(\mathbf{A} \cdot \mathbf{a}_s) = \mathbf{A} - \mathbf{A}_{\parallel} = \mathbf{A}_{\perp}$ .

### Problem 2

Given two vectors  $\mathbf{A} = \alpha\mathbf{a}_x + 3\mathbf{a}_y - 2\mathbf{a}_z$  and  $\mathbf{B} = 4\mathbf{a}_x + \beta\mathbf{a}_y + 8\mathbf{a}_z$ , determine  $\alpha$  and  $\beta$  such that

(a)  $\mathbf{A}$  and  $\mathbf{B}$  are **parallel**,

(b)  $\mathbf{A}$  and  $\mathbf{B}$  are **perpendicular**.

### Solution

(a)  $\mathbf{A}$  and  $\mathbf{B}$  are **parallel** implies that there is a constant  $k$  such that

$$\mathbf{A} = k\mathbf{B}.$$

It follows that

$$\alpha\mathbf{a}_x + 3\mathbf{a}_y - 2\mathbf{a}_z = 4k\mathbf{a}_x + k\beta\mathbf{a}_y + 8k\mathbf{a}_z,$$

Equating component by component yields the set of algebraic equations

$$\alpha = 4k; \quad 3 = k\beta, \quad 8k = -2. \quad (1)$$

It follows from Eq. (1) that

$$\alpha = -1, \quad \beta = -12.$$

(b) **A** and **B** are **perpendicular**, implying that

$$\mathbf{A} \cdot \mathbf{B} = 0 \quad (2)$$

It follows at once from Eq. (2) and the definition of scalar product in terms of vector components that

$$4\alpha + 3\beta - 16 = 0. \quad (3)$$

In other words, one can only say that possible values of  $\alpha$  and  $\beta$  must satisfy Eq. (3).

### Problem 3

*Express unit vectors in the Cartesian coordinates in terms of cylindrical coordinate unit vectors.*

#### Solution

Since  $\mathbf{a}_\rho = \boldsymbol{\rho}/\rho$ , we can simply express  $\mathbf{a}_\rho = \mathbf{a}_x \cos \phi + \mathbf{a}_y \sin \phi$ . Also  $\mathbf{a}_z$  is the same in both coordinate systems. As  $\mathbf{a}_\rho$ ,  $\mathbf{a}_\phi$  and  $\mathbf{a}_z$  form a right-hand set,  $\mathbf{a}_\rho \times \mathbf{a}_\phi = \mathbf{a}_z$ . It follows by a cyclic permutation that  $\mathbf{a}_\phi = -(\mathbf{a}_\rho \times \mathbf{a}_z) = -(\mathbf{a}_x \times \mathbf{a}_z) \cos \phi - (\mathbf{a}_y \times \mathbf{a}_z) \sin \phi = -\mathbf{a}_x \sin \phi + \mathbf{a}_y \cos \phi$ . Where we used the mutual orthogonality of  $\mathbf{a}_x$ ,  $\mathbf{a}_y$  and  $\mathbf{a}_z$ ,  $\mathbf{a}_x \times \mathbf{a}_y = \mathbf{a}_z$ . Thus,

$$\mathbf{a}_\rho = \mathbf{a}_x \cos \phi + \mathbf{a}_y \sin \phi,$$

and

$$\mathbf{a}_\phi = -\mathbf{a}_x \sin \phi + \mathbf{a}_y \cos \phi.$$

Solving the last two equations for  $\mathbf{a}_x$  and  $\mathbf{a}_y$ , we arrive at

$$\mathbf{a}_x = \mathbf{a}_\rho \cos \phi - \mathbf{a}_\phi \sin \phi,$$

and

$$\mathbf{a}_y = \mathbf{a}_\rho \sin \phi + \mathbf{a}_\phi \cos \phi.$$

### Problem 4

*Express unit vectors in the spherical coordinates in terms of the Cartesian coordinate system unit vectors.*

#### Solution

Recall that  $\mathbf{a}_r = \mathbf{r}/r = \mathbf{a}_x \sin \theta \cos \phi + \mathbf{a}_y \sin \theta \sin \phi + \mathbf{a}_z \cos \theta$ . We have also just determined  $\mathbf{a}_\phi$ , namely

$$\mathbf{a}_\phi = -\mathbf{a}_x \sin \phi + \mathbf{a}_y \cos \phi.$$

The mutual orthogonality of  $\mathbf{a}_r$ ,  $\mathbf{a}_\theta$  and  $\mathbf{a}_\phi$  dictates

$$\mathbf{a}_\theta = -(\mathbf{a}_r \times \mathbf{a}_\phi) = \mathbf{a}_\phi \times \mathbf{a}_r.$$

Using the mutual orthogonality of  $\mathbf{a}_x$ ,  $\mathbf{a}_y$  and  $\mathbf{a}_z$ , we obtain after little algebra,

$$\mathbf{a}_\theta = \mathbf{a}_x \cos \phi \cos \theta + \mathbf{a}_y \sin \phi \cos \theta - \mathbf{a}_z \sin \theta.$$